Drone IBus Channel Configurations

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| Channel | Axis/Purpose | Configuration |
| Ch1 | Roll | -100 <-> 0 <-> 100 |
| Ch2 | Pitch | -100 <-> 0 <-> 100 |
| Ch3 | Throttle | 0 <-> 100 |
| Ch4 | Yaw | -100 <-> 0 <-> 100 |
| Ch5 | State | 0 <-> 1 (whichever its closest too |

IBus Structure State 1 means theres been input to read from RF Controller